



Easy operation, Full functionality

【 All Types 】

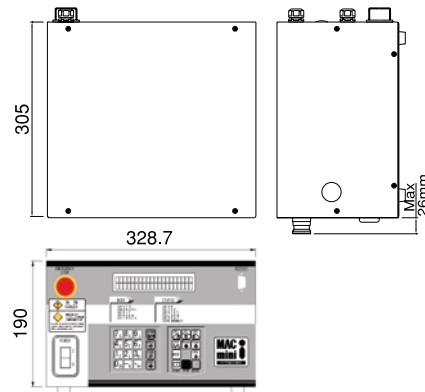
- **Absolute Encoders are adopted to all types.**
Absolute encoders of 17 bits are used on all MAC mini controllers. This means it is not necessary to return to the zero position after each power on. The machine zero position can also be optionally set at any angle. If the cable from the rotary table is disconnected from the controller the zero position still remains.
- **LCD can display various data.**
The LCD screen is used to display various data. Programs can be displayed by each block. Parameter settings and alarm messages are displayed clearly with descriptions making setup, programming and error finding simple.
- **Max. 90 channels capacity.**
Standard 16 channels can be expanded to 90 by setting the number of blocks per channel.
- **1000 blocks per channel.**
Each program created in one channel can contain 1000 blocks.
- **Manual pulse generator.**
Manual pulse generators can be fitted as an option.
- **Extend reset function can be installed.**

【 MAC mini iH Type: CE Compliant. 】

- **Pendant type features manual operation.**
All features, programming editing, diagnostics etc can be operated from the product.
- **ENABLE switch function**
The pendant is equipped with an ENABLE switch as standard for safe operation in manual mode and automatic mode.
- **External channel number output.**
The channel number that is selected can be outputted to external equipment, this allows the selected channel number to be checked on the machine side.
- **Controller corresponding to 2 axes (MAC mini iH2 / iHT)**
2 axis controller. One controller can control 2 axis. One common M signal can also correspond to 2 axis.
- **Many outputs of function signals.**
Output of auto signals, output of manual signals etc.

MAC mini i / iF / IDM

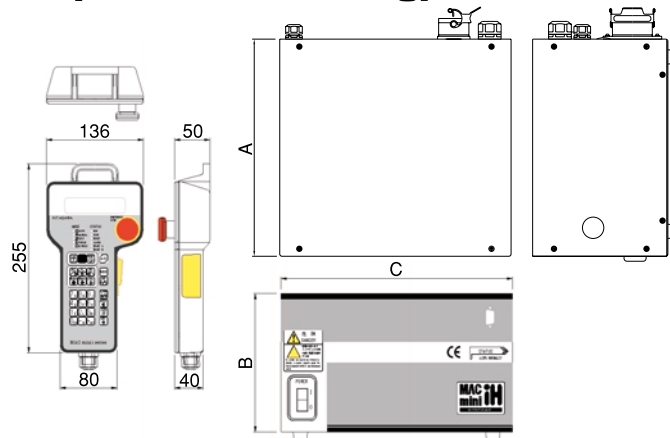
[Dimensional drawing]



MAC mini iH / iHF / iHP

Conforms to EN standard and corresponds to EMC command.

[Dimensional drawing]



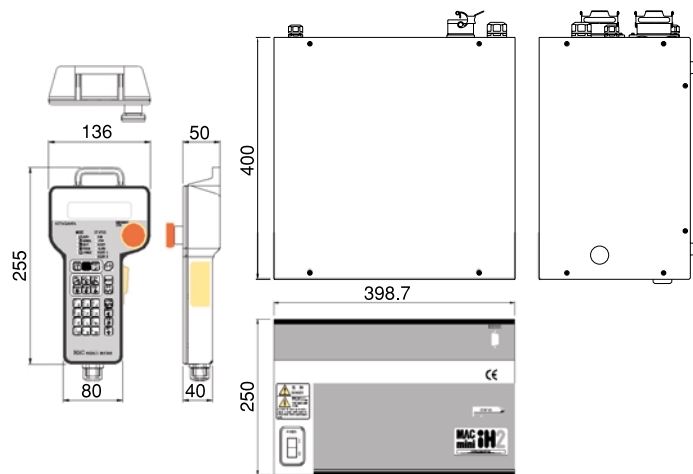
■ Dimensions

	A	B	C
iH / iHF	305	190	328.7
iHP	400	250	398.7

MAC mini iH2 / iHT

Two-axis controller conformed to EN standard and corresponded to EMC command.

[Dimensional drawing]

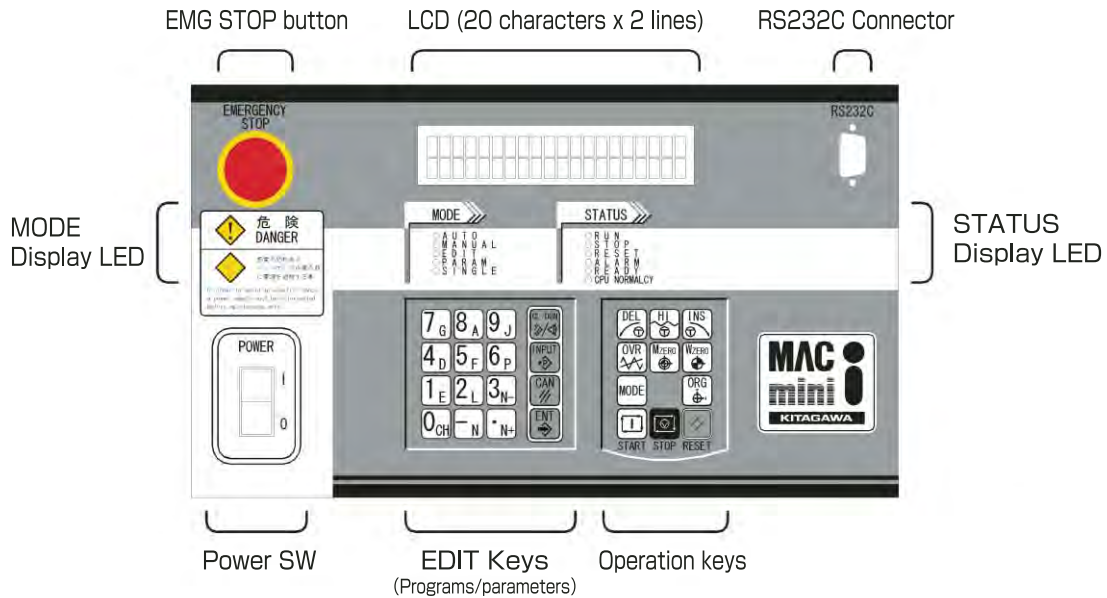




MAC mini i series

MAC mini i · MAC mini iH · MAC mini iH2

MAC mini i Type PANEL FUNCTIONS



- **Power SW** Turns ON/OFF controller power.
- **EMG STOP button** Stops the table during operation in an emergency.
- **LCD** Displays current position, program, parameter and alarm data.
 [Current position display example]
 CH00 A 123.456
 N000 WP-R
 [Program display example]
 CH00 /A/G90A180.000
 N000 F0 D J
 [Parameter display example]
 A:110 1
 PRM INPUT PERMISSION
 [Alarm display example]
 <A>Err.001
 EMERGENCY STOP
 [Diagnosis screen display example]
 A 011000 CLAMP
 EA-I
- **RS232C Connector** Uses this connector when data communication or remote control is performed.
- **MODE Display LED**
 - AUTO : Auto operation mode**
Executes block by block as often as a start signal is inputted.
 - MANUAL : Manual operation mode**
Rotates the table manually.
 - EDIT : Program EDIT mode**
Inputs and edits programs.
 - PARAM : Parameter mode**
Sets and checks parameters.
 - SINGLE : Manual operation**
Operates the controller independently.

- **STATUS Display LED**
 - RUN : During RUN**
Lamp lights during program run.
 - STOP : During STOP**
Lamp lights when program is not run. When the program is held, the lamp lights together with "RUN".
 - RESET : During RESET**
Lamp lights just after power ON, after program reset and JOG start.
 - ALARM : During alarm occurrence**
Lamp lights during alarm. The lamp flashes while alarms occur redundantly.
 - READY : Operation ready**
Lamp lights when the controller can be operated automatically.
- **EDIT Keys** Used when program INPUT/EDIT, parameter setting and selection of diagnosis screen are performed.
- **Operation keys**
 - Selects operation mode.
 - Feeds at JOG in CW direction.
 - Feeds at JOG in CCW direction.
 - Feeds at high JOG speed when pressing this button together with or .
 - Rotates to MZRN position.
 - Rotates to WZRN position.
 - Starts the program.
 - Stops the program.
 - Resets the program or alarm.
 - Sets WZRN position.
 - Sets the override of feedrate.

MAC mini iH Type PENDANT FUNCTIONS



■ EMG STOP button

Stops the table during operation in an emergency.

■ ENABLE switches

Be sure to press ENABLE switches for safety operation and to prevent malfunction in auto operation start before an automatic operation is started by manual operation or pendant operation.

■ LCD

Displays current position, program, parameter and alarm data.

[Current position display example]

CH00 A 123.456
N000 WP-R

[Program display example]

CH00 /A/G90A180.000
N000 F0 D J

[Parameter display example]

A:110 1
PRM INPUT PERMISSION

[Alarm display example]

<A>Err. 001
EMERGENCY STOP

[Diagnosis screen display example]

A 011000 CLAMP
EA-I

■ EDIT Keys

Used when program INPUT/EDIT, parameter setting and selection of diagnosis screen are performed.

■ MODE Display LED

- AUTO** : Auto operation mode
Executes block by block as often as a start signal is inputted.
- MANUAL** : Manual operation mode
Rotates the table manually.
- EDIT** : Program EDIT mode
Inputs and edits programs.
- PARAM** : Parameter mode
Sets and checks parameters.
- SINGLE** : Manual operation
Operates the controller independently.

■ STATUS Display LED

- RUN** : During RUN
Lamp lights during program run.
- STOP** : During STOP
Lamp lights when program is not run. When the program is held, the lamp lights together with "RUN".
- RESET** : During RESET
Lamp lights just after power ON, after program reset and JOG start.
- ALARM** : During alarm occurrence
Lamp lights during alarm. The lamp flashes while alarms occur redundantly.
- READY A** : A-axis operation ready
Lamp lights when A-axis can be operated automatically.
- READY B** : B-axis operation ready
Lamp lights when B-axis can be operated automatically.
When MAC mini iH2/iHT are used, B-axis is used.

■ Operation keys

- Selects operation mode.
- Feeds at JOG in CW direction.
- Feeds at JOG in CCW direction.
- Feeds at high JOG speed when pressing this button together with or .
- Rotates to MZRN position.
- Rotates to WZRN position.
- Starts the program.
- Stops the program.
- Resets the program or alarm.
- Sets WZRN position.
- Sets the override of feedrate.

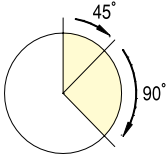
■ Axis change keys

- When MAC mini iH2/iHT are manually operated and programs/parameters are edited, A-axis is changed with B-axis and vice versa.



PROGRAM EXAMPLES

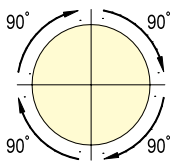
ANGLE INDEX



```
N000 A 45.000 F0
      Index angle Rapid traverse
N001 A 90.000 J0
      Jump destination
```

Rotates 45° at rapid traverse and returns to N000 after rotating 90°.

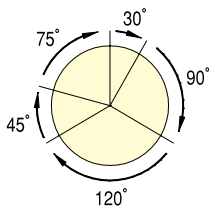
EQUIPARTITION



```
N000 A360.000 F0 D4 J0
      Partition angle Divided partition
```

Rotates with circle of 360° divided into 4-partition (every 90°) at rapid traverse and returns to N000 after operating 4 times.

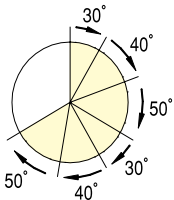
UNEQUAL PARTITION



```
N000 A 30.000 F0
N001 A 90.000
N002 A 120.000
N003 A 45.000
N004 A 75.000 F500 J0
      Feedrate
```

Rotate 45° at rapid traverse, 90°, 120°, 45° and 75° at feedrate 5.00min⁻¹ before returning to N000.

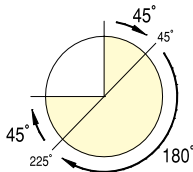
REPETITION



```
N000 G27 P10 E12 L2
      Repeating Repeating Repeating Repeating
      command start block end block times
N010 A 30.000
N011 A 40.000
N012 A 50.000
```

Command that repeats content of N010~N012. Rotate 30°, 40° and 50°.

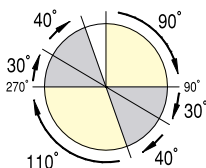
ABSOLUTE / INCREMENTAL



```
N000 G90 A 45.000 F0
      ABS Index position
      command
N001 A225.000
      Index position
N002 G91 A 45.000
      INC Index angle
      command
```

Rotates 45° at rapid traverse under absolute mode. Rotates 225°. Rotates 45° under incremental mode.

SUBPROGRAM



```
N000 A 90.000 F0 J10
      Subprogram jump destination
N001 G90 A270.000 J10
      Subprogram jump destination
N002 J0
      Return command
N010 G91 A 30.000
N011 A40.000 J-1
      Return command
```

Rotates 90° at rapid traverse and jumps to N010. Rotates 270° under absolute command and jumps to N010. Returns to N000. Rotates 30° under incremental command, rotates 40° and returns to original subprogram jump command point.

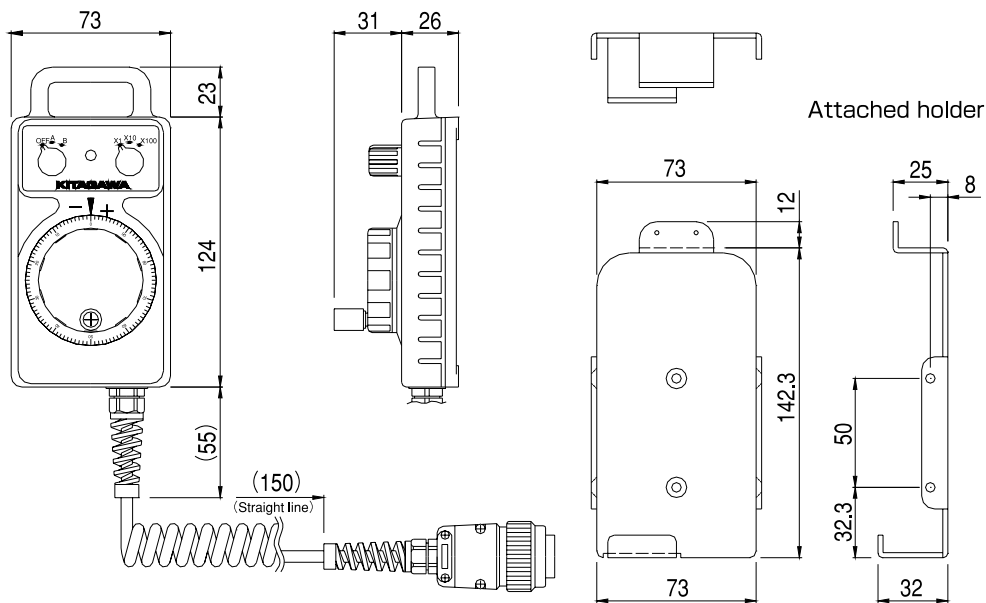
MAC mini i Series OPTION

Manual Pulse Generator



[HC11DAKC11]

This pulse generator can operate the table at 0.1°, 0.01° and 0.001°, and it adjusts jigs easily. One pulse generator can operate MAC mini iH2/iHT by changing the shaft.

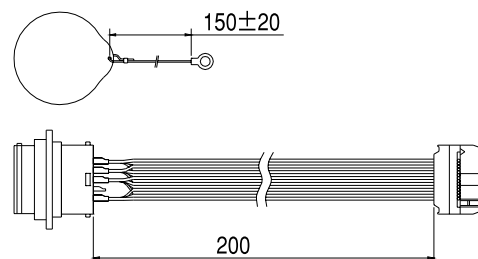


Manual Pulse Generator Junction cable

To use the manual pulse generator, this junction cable (for inside panel) is required.

For HC1-IC, dust caps and mounting screws (4 pieces) are attached.

[HC1-IC]



Dedicated software for data communication

This software can input and output the data for "Program", "Parameter" and "WZRN POS." that stores them in the controller.

This software is for Windows and it corresponds to WindowsXP, NT4.0 and 2000.

For RS232C cable, please consult our Sales Section.

[Updown Load]





MAC mini i Series MAC mini i · MAC mini iH · MAC mini iH2

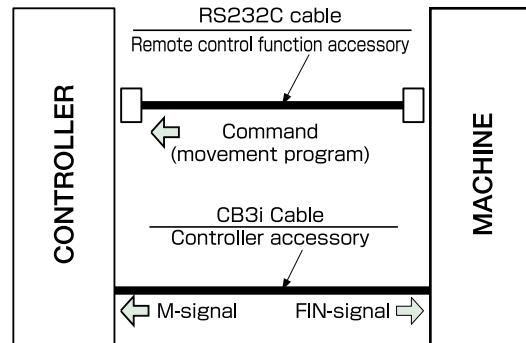
MAC mini i Series OPTION

Remote Control Function

Remote Control Mode

The rotary table is controlled by programming the table movement into the machine's NC program. There is no programming required on the controller.

The movement of the rotary table is controlled by the program on the machine.



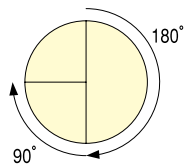
NC maker and Required function

NC maker	Required Function (※1)	NC unit type
FANUC	Custom macro B (External output command)	After FSO series After FS11 series
Mitsubishi Electric Corporation	User macro (External output command)	After MELDAS300 series
Okuma	User task II READ/WRITE · GET/PUT functions	After OSP5000
Yamazaki Mazak Corporation	External output command	Fusion 640M MATRIX ※2

※1 Since the required function may be the option of NC unit, please check that the required function exists to each maker.
 ※2 RS232C extension is required.

Examples of Machine Programs

● Program: FANUC (external output command)



```

    POPEN;
    DPRNT [//G91A180.000F30.00/];
    PCLOS;
    M100;
    .....
    POPEN;
    DPRNT [//G91A90.000F0.00/];
    PCLOS;
    M100;
    
```

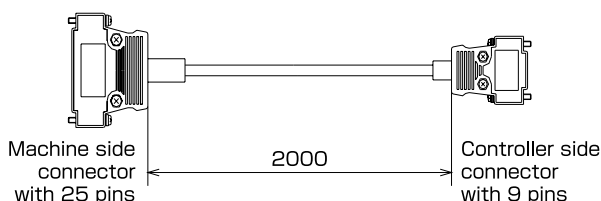
Open RS232C port.
 Transmit movement command to controller.
 Close RS232C port.
 Start positioning.
 Process by movement program on the machine
 Open RS232C port.
 Transmit movement command to controller.
 Close RS232C port.
 Start positioning.

Remote Control Function Accessory

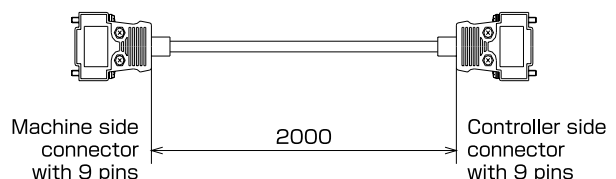
● RS232C cable for remote controlling

RS232C cable to connect between the machine and the controller.
 Select the cable with appropriate connector type to match RS232C port on the machine.

[RSCB0925] (Standard)



[RSCB0909] (Made to order)



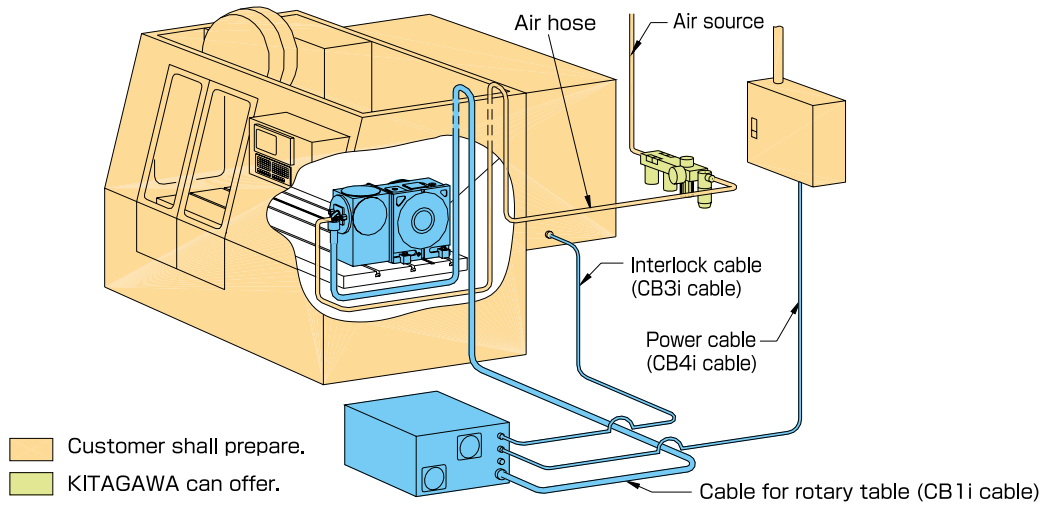
MAC mini i Series Specification

Item	MAC mini	Standard specification			CE specification				
		i	iDM	iF	iH	iHF	iHP	iH2	iHT
Controlled axes		1 axis			1 axis			2 axes	
Servomotor spec.		AC servo motor with absolute detector							
Servomotor capacity		750W	200W	400W	750W	400W	2KW	750W+750W	400W+750W
Setting unit		0.001°							
Max. setting angle		999-rotation +360° and 999,999°							
Equal partition		2~999 partition (dividable to sector form)							
Program capacity		2000-block (500-block x 1CH + 100-block x 15CH: Standard) ■ Optional channel set function is usable at max. 90-CH, max. 1000-block (1CH).							
Command method		Absolute / incremental methods (selectable at G90 / G91)							
Zero position return		MZRN and WZRN			MZRN and WZRN (commandable by external input.)				
Manual feed		Rapid traverse, slow speed feed, step feed							
Emergency stop		Emergency stop button or forced servo stop by external interlock input + master stop ■ When an emergency stop button is pushed, the data is outputted(EMOUT) to the external equipment.							
Halt		Halt of rotary table by key input or external SP input							
Feedrate override		Settable to 1~200% (Can be notched to 1~100%.)							
Preparatory function		DWEELL, LEAD CUTTING, BUFFER FUNCTION, CLAMP PRESENCE, DEVIATION CHECK FUNCTION, INTERLOCK START, CONTINUOUS START, MZRN, WZRN, REPEATING FUNCTION, LOOP JUMP FUNCTION, ABSOLUTE/INCREMENTAL, FIN SIGNAL CONTROL COMMAND							
Jump function		Jumps to subprogram.							
Uni-directional approach		Even if rotary direction is changed, positioning from uni-direction is available.							
Software limit function		Software limit can be set from machine zero position to prevent interference with the machine by mounting jigs or workpiece.							
Over travel stop function		The hard limit mode can control the rotary range of rotary table. Inputted point : 1 point Inputted point : 2 points							
Pitch error compensation		Pitch error can be compensated per 15°. (Min. set unit : 0.001°)							
Backlash compensation		The backlash compensation of rotary table can be set. (Min. set unit : 0.001°)							
Alarm function		When error is detected, alarm No. and alarm message are automatically displayed.							
Self-diagnosis function		Machine coordinate, work coordinate (command value, encoder value), remained movement, I/O signal state, position deviation, current %, encoder electric angle							
Input power		Single-phase AC200/230V±10% 50/60 Hz (Only iHP : 3 phases, AC200/230V±10% 50/60Hz)							
Apparent power		1.0KVA	0.6KVA		1.0KVA	0.6KVA	4.3KVA	2.0KVA	1.6KVA
Weight		7.5kg			14kg		27kg	24kg	
Environment		Working temperature : 0~45°C Humidity: 85%RH or less (dew condensation, freezing not to be found.) Vibration proof: 0.5G or less				Storage temperature (transportation temp.) : -10°C ~60°C Shock resistant: 1G or less Ambient atmosphere : to pollution level 2			
Display		LCD 20 characters x 2 lines							
Attached cables		<ul style="list-style-type: none"> •Rotary table~controller Polyamide flexible cable ● 5m •Power cable 5m •External interlock cable ● 5m 			<ul style="list-style-type: none"> •Rotary table~controller Polyamide flexible cable with metal blade ● 5m •Power cable 5m •External interlock cable ● 5m 			<ul style="list-style-type: none"> •Rotary table~controller Two polyamide flexible cables with metal blade ● 5m •Power cable 5m •External interlock cable ● 5m 	
External input signal		START, STOP External EMG STOP, external channel selection			START, STOP, RESET External EMG STOP, external channel selection external ZRN, AUTO/MANU mode change			START, STOP, RESET External EMG STOP, external channel selection external ZRN (A-axis / B-axis) AUTO / MANU mode change	
External output signal		Block completed, 360° comp., optional completed signal, MZRN completed, EMG STOP output signal, alarm output signal (A-contact, B-contact)			Block completed, 360° comp., optional completed signal, MZRN completed, EMG STOP output signal, alarm output signal (A-contact, B-contact), channel No. output			【Common output】 Block completed, EMG STOP output signal, channel No. output, alarm output signal (A-contact, B-contact), 【A/B each axis output】 360° comp., optional completed signal, MZRN completed	
RS232C Interface		External equipment can input and output programs, parameters, etc. Interface is also used for the remote control function.							

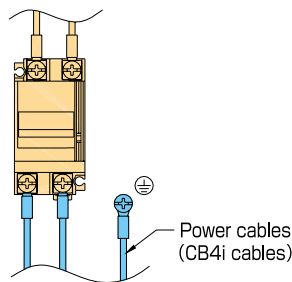
Note) Minimum federate is at 0.03min⁻¹.



Connection



Power Supply



Supply power to controller.
 Customer shall prepare exclusive circuit breaker.
 Specifications of circuit breaker are as follows:

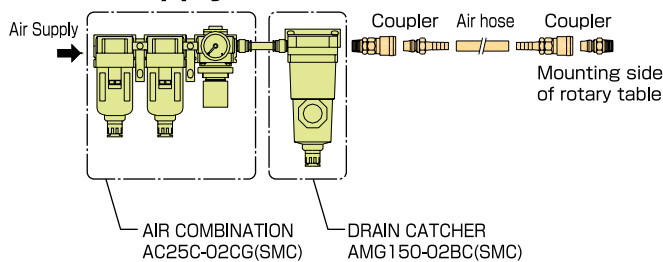
Type	Capacity
MAC mini iF / iHF / iDM	5A
MAC mini i / iH	10A
MAC mini iH2 / iHT	15A
MAC mini iHP	30A

Connect an earth wire of Class D (Class No. 3).
 Moreover, when the earth leakage breaker is used, it is recommended to use the breaker for which sensitivity current is 100mA or more, an operation time is 0.1 second or more, or a high frequency measure is taken in order to prevent the motor from the malfunction caused by a motor's high frequency.

Connection for external interlock

When the rotary table is interlocked with the external equipment, it is controlled with M signals from the external equipment.
 The external equipment must be equipped with the connection (terminal board) for M-signal OUTPUT, M-signal completed INPUT, etc., by machine maker.

Air Supply

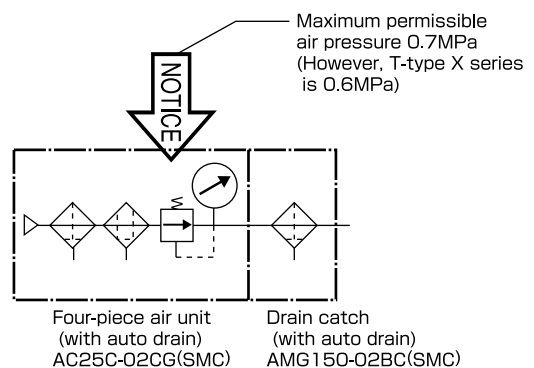


The rotary table is clamped by air.
 Therefore, please prepare the following components.

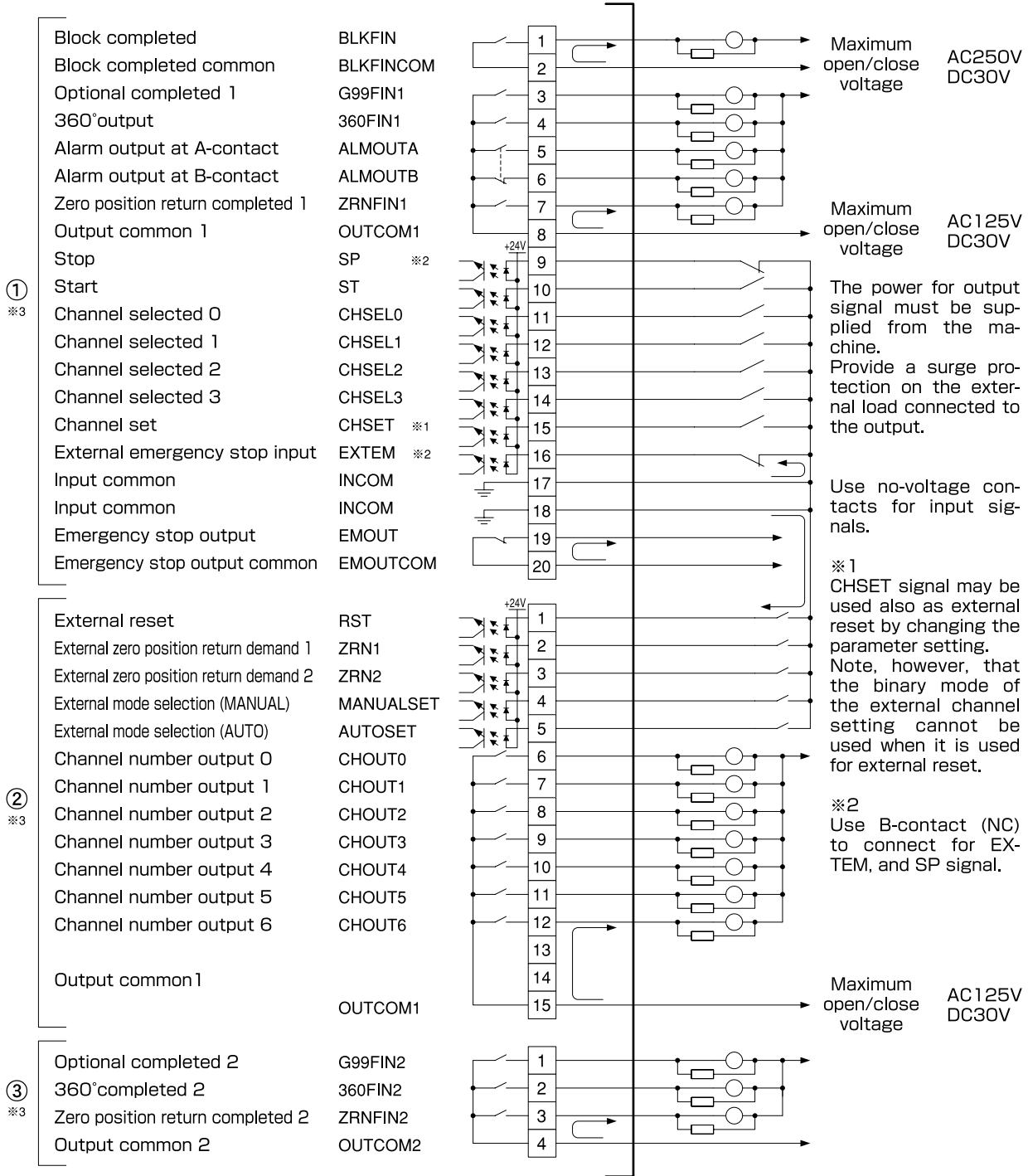
- Air combination
- Drain unit
- Air hoses or air tubes (incombustibility)
- Couplers for connection

※Air-Unit should have the specification with Auto drain port

Air Diagram



Mutual Connection Diagram



※3
MAC mini i series may have different I/O signals depending on the machine types.

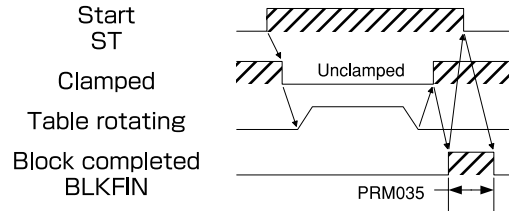
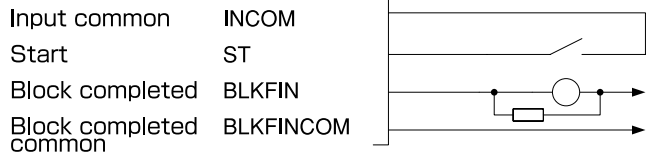
	I/O Signal Configurations		
	①	②	③
MAC mini i / iF / iDM	○	—	—
MAC mini iH / iHF / iHP	○	○	—
MAC mini iHT / iH2	○	○	○

Extension not available for configurations marked with "—".

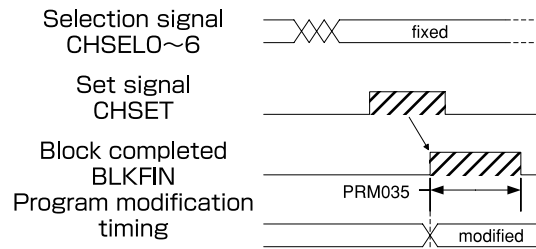
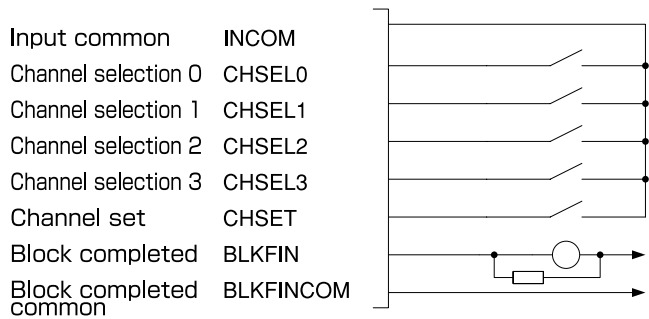


Machine Connection Diagram

M-Signal Interlock

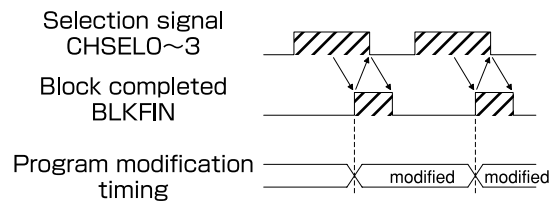
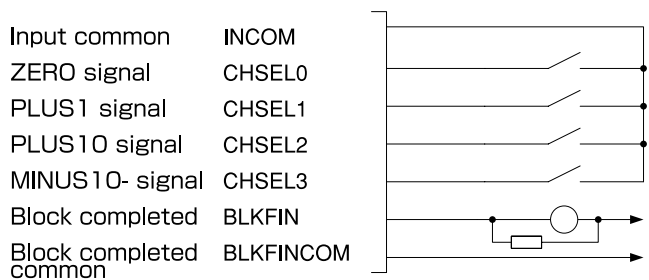


External Program Selection: Binary Mode



※The channels available on binary mode are CH00 through CH15.

External Program Selection: M-signal Mode

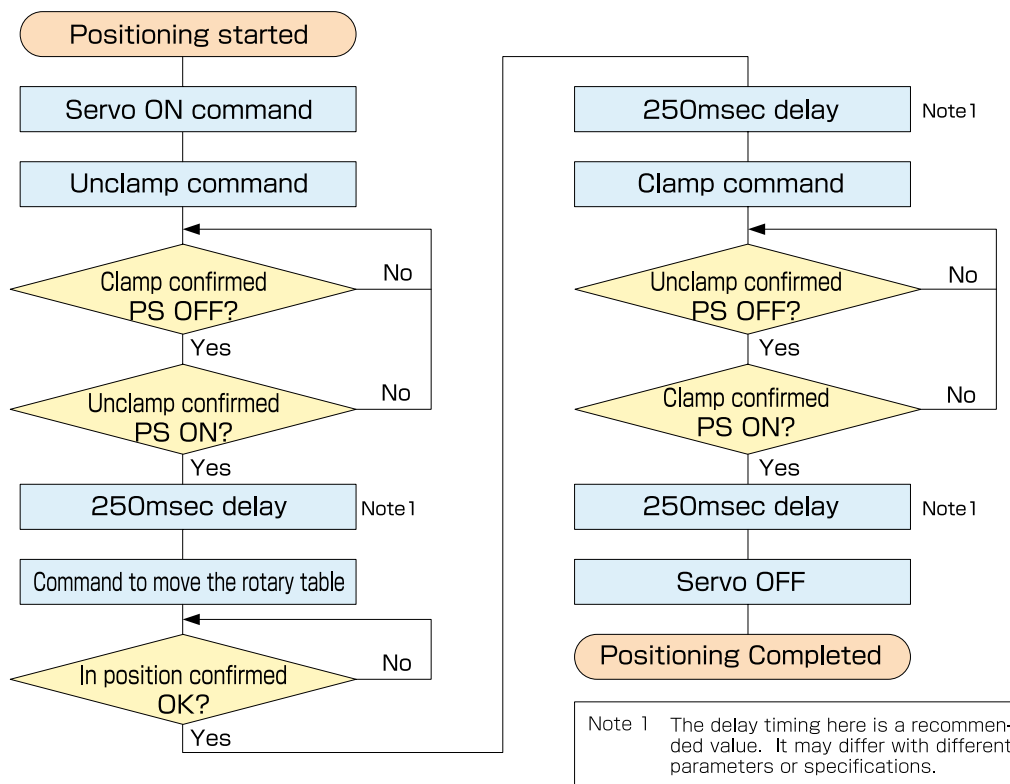


※The channels available on M-signal mode are CH00 through CH89.
For CH16 and later, extension channel setting is required.

Control Flow-Chart

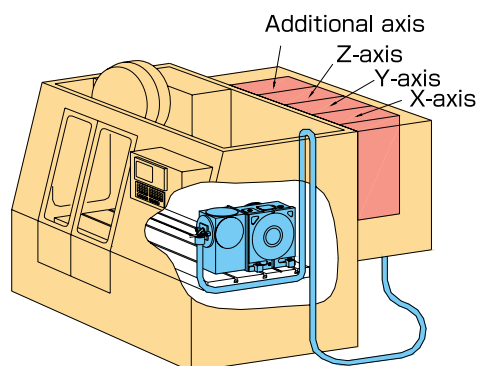
It is in principle recommended for Kitagawa's NC rotary table control to turn the servo OFF while clamping.

Semi-/Full-Closed Loop



Methods for Controlling NC Rotary Table

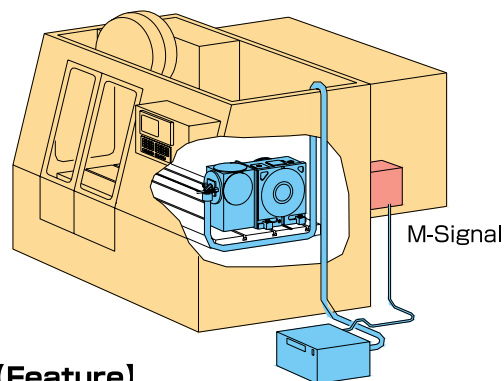
Additional-Axis Method



[Feature]

- ◆ NC Rotary Table is controlled as the NC Axis of the machine.
- ◆ Interpolation machining is possible with X-, Y- and Z-axis of the machine.
- ◆ Program can be controlled on the machine.

M-Signal Method



[Feature]

- ◆ NC Rotary Table is controlled by a separate controller, and not as the NC Axis of the machine.
- ◆ NC Rotary Table can be fitted with machine with no compatibility for an additional axis, as long as M-signal is available.
- ◆ NC Rotary Table can easily be transferred to another machine.